## 具有超低 I<sub>Q</sub> 的 LM5163 100V 输入、0.5A 同步降压直流/直流转换器

## 1 特性

- 专为可靠耐用的应用设计
  - 6V 至 100V 的宽输入电压范围
  - 结温范围: -40°C 至 +150°C
  - 固定 3ms 内部软启动计时器
  - 峰值和谷值电流限制保护
  - 输入 UVLO 和热关断保护
- 适用于可扩展的工业电源和电池组
  - 最短导通时间和关闭时间低: 50ns
  - 高达 1MHz 的可调节开关频率
  - 可实现高轻负载效率的二极管仿真
  - 10.5µA 空载输入静态电流
  - 3µA 关断静态电流
- 超低 EMI 辐射
  - 针对 CISPR 25 5 类 标准进行了优化
- 通过集成技术减小解决方案尺寸,降低成本
  - COT 模式控制架构
  - 集成式 0.725Ω NFET 降压开关
  - 集成式 0.34Ω NFET 同步整流器省去了外部肖特基二极管
  - 1.2V 内部电压基准
  - 无环路补偿组件
  - 内部 VCC 偏置稳压器和自举二极管
  - 漏极开路电源正常指示器
  - 带 PowerPAD™ 的 8 引脚 SOIC 封装
- 使用 WEBENCH<sup>®</sup> 电源设计器创建定制稳压器设计

 $V_{OUT} = 12 V$ L<sub>0</sub> 120 μH U<sub>1</sub>  $I_{OUT} = 0.5 \text{ A}$ V<sub>IN</sub> = 6 V...100 V VIN sw CBST LM5163 CIN 2.2 nF R<sub>FB1</sub> EN/UVLO BST 448 kΩ ≥  $2.2\,\mu\text{F}$ COUT 22 µF RON FB  $R_{\text{RON}}$ 100 kΩ <  $R_{FB2}$ 49.9 kΩ GND PGOOD \*V<sub>OUT</sub> tracks V<sub>IN</sub> if V<sub>IN</sub> < 12 V

### 2 应用

- 工业电池组 (≥10S)
- 电池组 电动自行车/电动踏板车/LEV
- 电机驱动器、无人机、通信设备

### 3 说明

LM5163 同步降压转换器用于在宽输入电压范围内进行 调节,从而最大限度地减少对外部浪涌抑制组件的需 求。50ns 的最短可控导通时间有助于实现较大的降压 比,支持从 48V 标称输入到低电压轨的直接降压转 换,从而降低系统的复杂性并减少解决方案成本。 LM5163 在输入电压突降至 6V 时能够根据需要以接近 100% 的占空比继续工作,使其成为宽输入电源范围工 业和高电池节数电池组 应用的理想选择。

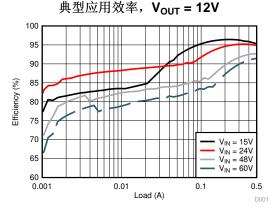
LM5163 具有集成式高侧和低侧功率 MOSFET,可提 供高达 0.5A 的输出电流。恒定导通时间 (COT) 控制 架构可提供几乎恒定的开关频率,具有出色的负载和线 路瞬态响应。其他 特性 LM5163 的其他特性包括超低 I<sub>Q</sub> 和二极管仿真模式运行(可实现高轻负载效率)、 创新的峰值和谷值过流保护、集成式 VCC 偏置电源和 自举二极管、精密使能和输入 UVLO 以及具有自动恢 复功能的热关断保护。开漏 PGOOD 指示器可提供进 行定序、故障报告和输出电压监视功能。

LM5163 采用热增强型 8 引脚 SO PowerPAD<sup>™</sup> 封 装。其 1.27mm 引脚间距可以为高电压 应用的实施。

器件信息の					
器件型号	封装	封装尺寸(标称值)			
LM5163	SO PowerPAD (8)	4.89mm × 3.90mm			

нн *и* и, н. н. (1)

(1) 如需了解所有可用封装,请参阅数据表末尾的可订购产品附录。



典型应用

## 目录

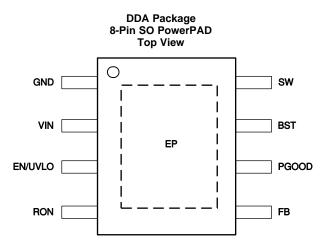
1	特性	
2	应用	1
3	说明	1
4		历史记录
5		Configuration and Functions 3
6	Spe	cifications 4
	6.1	Absolute Maximum Ratings 4
	6.2	ESD Ratings 4
	6.3	Recommended Operating Conditions 4
	6.4	Thermal Information 5
	6.5	Electrical Characteristics5
	6.6	Typical Characteristics7
7	Deta	ailed Description
	7.1	Overview
	7.2	Functional Block Diagram 10
	7.3	Feature Description 10
	7.4	Device Functional Modes 15

8	Appli	ication and Implementation	16
	8.1	Application Information	16
		Typical Application	
9		er Supply Recommendations	
10		put	
		Layout Guidelines	
	10.2	Layout Example	26
11	器件	和文档支持	27
	11.1	器件支持	27
	11.2	相关文档	27
	11.3	接收文档更新通知	27
	11.4	支持资源	28
	11.5	商标	28
	11.6	静电放电警告	28
	11.7	Glossary	28
12	机械	、封装和可订购信息	28

## 4 修订历史记录

日期	修订版本	说明	
2019 年 10 月	*	初始发行版	

## 5 Pin Configuration and Functions



#### **Pin Functions**

P	PIN		PIN I/O <sup>(1)</sup>		DESCRIPTION		
NO.	NAME	1/0 ( )	DESCRIPTION				
1	GND	G	Ground connection for internal circuits				
2	VIN	P/I	Regulator supply input pin to high-side power MOSFET and internal bias regulator. Connect directly to the input supply of the buck converter with short, low impedance paths.				
3	EN/UVLO	I	Precision enable and undervoltage lockout (UVLO) programming pin. If the EN/UVLO voltage is below 1.1 V, the converter is in shutdown mode with all functions disabled. If the UVLO voltage is greater than 1.1 V and below 1.5 V, the converter is in standby mode with the internal VCC regulator operational and no switching. If the EN/UVLO voltage is above 1.5 V, the start-up sequence begins.				
4	RON	I	On-time programming pin. A resistor between this pin and GND sets the buck switch on-time.				
5	FB	I	Feedback input of voltage regulation comparator				
6	PGOOD	0	Power good indicator. This pin is an open-drain output pin. Connect to a source voltage through an external pullup resistor between 10 k $\Omega$ to 100 k $\Omega$ .				
7	BST	P/I	Bootstrap gate-drive supply. Required to connect a high-quality 2.2-nF 50-V X7R ceramic capacitor between BST and SW to bias the internal high-side gate driver.				
8	SW	Ρ	Switching node that is internally connected to the source of the high-side NMOS buck switch and the drain of the low-side NMOS synchronous rectifier. Connect to the switching node of the power inductor.				
_	EP	—	Exposed pad of the package. No internal electrical connection. Solder the EP to the GND pin and connect to a large copper plane to reduce thermal resistance.				

(1) G = Ground, I = Input, O = Output, P = Power

## 6 Specifications

## 6.1 Absolute Maximum Ratings

Over the recommended operating junction temperature range of -40°C to +150°C (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
	VIN to GND	-0.3	100	
	EN to GND	-0.3	100	V
Input voltage	FB to GND	-0.3	5.5	V
	RON to GND	-0.3	5.5	
Bootstrap capacitor	External BST to SW capacitance	1.5	2.5	nF
	BST to GND	-0.3	105.5	
	BST to SW	-0.3	5.5	
Output voltage	SW to GND	-1.5	100	V
	SW to GND (20-ns transient)	-3		
	PGOOD to GND	-0.3	14	
Operating junction temperature, T <sub>J</sub>		-40	150	°C
Storage temperat	ure, T <sub>stg</sub>	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 6.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	v

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 6.3 Recommended Operating Conditions

Over the recommended operating junction temperature range of -40°C to +150°C (unless otherwise noted)<sup>(1)</sup>

		MIN	NOM	MAX	UNIT
V <sub>IN</sub>	Input voltage	6		100	V
V <sub>SW</sub>	Switch node voltage			100	V
V <sub>EN/UVLO</sub>	Enable voltage			100	V
ILOAD	Load current		0.5	0.6	А
F <sub>SW</sub>	Switching frequency			1000	kHz
C <sub>BST</sub>	External BST to SW capacitance		2.2		nF
t <sub>ON</sub>	Programmable on-time	50		10000	ns

## 6.4 Thermal Information

		LM5163	
	THERMAL METRIC	DDA (SOIC)	UNIT
		8 PINS	
$R_{ heta JA}$	Junction-to-ambient thermal resistance	43.4	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	59.5	°C/W
$R_{ heta JB}$	Junction-to-board thermal resistance	16.1	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	4.0	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	16.3	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	3.9	°C/W

## 6.5 Electrical Characteristics

Typical values correspond to  $T_J = 25^{\circ}$ C. Minimum and maximum limits apply over the full –40°C to 150°C junction temperature range unless otherwise indicated.  $V_{IN} = 24$  V and  $V_{EN/UVLO} = 2$  V unless otherwise stated.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CUP	RRENT					
I <sub>Q-SHUTDOWN</sub>	VIN shutdown current	V <sub>EN</sub> = 0 V		3	15	μA
I <sub>Q-SLEEP1</sub>	VIN sleep current	V <sub>EN</sub> = 2.5 V, V <sub>FB</sub> = 1.5 V		10.5	25	μA
I <sub>Q-ACTIVE</sub>	VIN active current	V <sub>EN</sub> = 2.5 V		600	880	μA
EN/UVLO						
V <sub>SD-RISING</sub>	Shutdown threshold	V <sub>EN/UVLO</sub> rising			1.1	V
V <sub>SD-FALLING</sub>	Shutdown threshold	V <sub>EN/UVLO</sub> falling	0.45			V
V <sub>EN-RISING</sub>	Enable threshold	V <sub>EN/UVLO</sub> rising	1.45	1.5	1.55	V
V <sub>EN-FALLING</sub>	Enable threshold	V <sub>EN/UVLO</sub> falling	1.35	1.4	1.44	V
FEEDBACK						
V <sub>REF</sub>	FB regulation voltage	V <sub>FB</sub> falling	1.181	1.2	1.218	V
TIMING						
t <sub>ON1</sub>	On-time1	$V_{VIN} = 6 V, R_{RON} = 75 k\Omega$		5000		ns
t <sub>ON2</sub>	On-time2	$V_{VIN} = 6 V, R_{RON} = 25 k\Omega$		650		ns
t <sub>ON3</sub>	On-time3	$V_{VIN}$ = 12 V, $R_{RON}$ = 75 k $\Omega$		2550		ns
t <sub>ON4</sub>	On-time4	$V_{VIN}$ = 12 V, $R_{RON}$ = 25 k $\Omega$		830		ns
PGOOD						
V <sub>PG-UTH</sub>	FB upper threshold for PGOOD high to low	V <sub>FB</sub> rising	1.105	1.14	1.175	V
V <sub>PG-LTH</sub>	FB lower threshold for PGOOD high to low	V <sub>FB</sub> falling	1.055	1.08	1.1	V
V <sub>PG-HYS</sub>	PGOOD upper and lower threshold hysteresis	V <sub>FB</sub> falling		60		mV
R <sub>PG</sub>	PGOOD pulldown resistance	V <sub>FB</sub> = 1 V		30		Ω
BOOTSTRAP	)					
V <sub>BST-UV</sub>	Gate drive UVLO	V <sub>BST</sub> rising		2.7	3.4	V
POWER SWI	TCHES	·				
R <sub>DSON-HS</sub>	High-side MOSFET R <sub>DSON</sub>	I <sub>SW</sub> = -100 mA		0.725		Ω
R <sub>DSON-LS</sub>	Low-side MOSFET R <sub>DSON</sub>	I <sub>SW</sub> = 100 mA		0.33		Ω

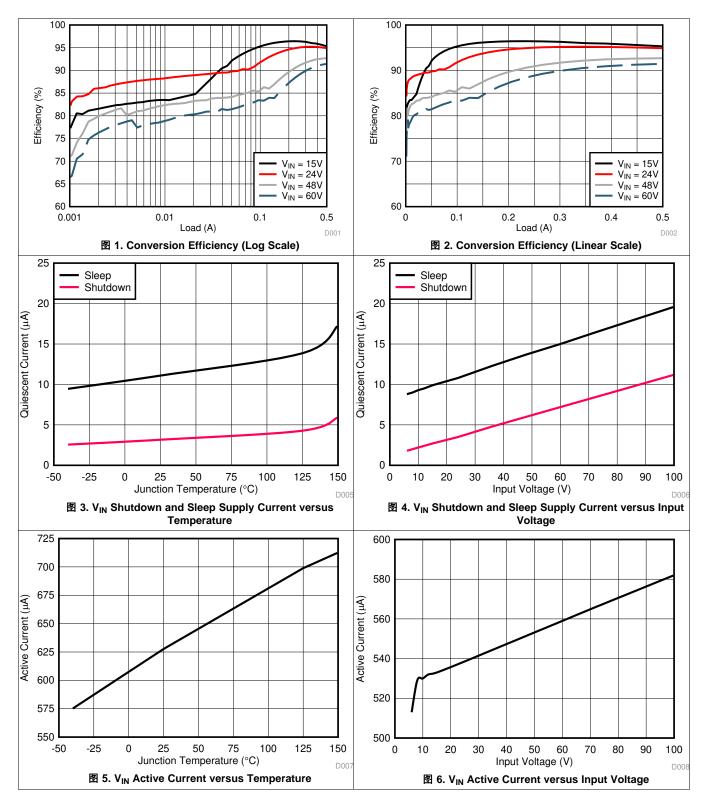
## **Electrical Characteristics (continued)**

Typical values correspond to  $T_J = 25^{\circ}$ C. Minimum and maximum limits apply over the full  $-40^{\circ}$ C to  $150^{\circ}$ C junction temperature range unless otherwise indicated.  $V_{IN} = 24$  V and  $V_{EN/UVLO} = 2$  V unless otherwise stated.

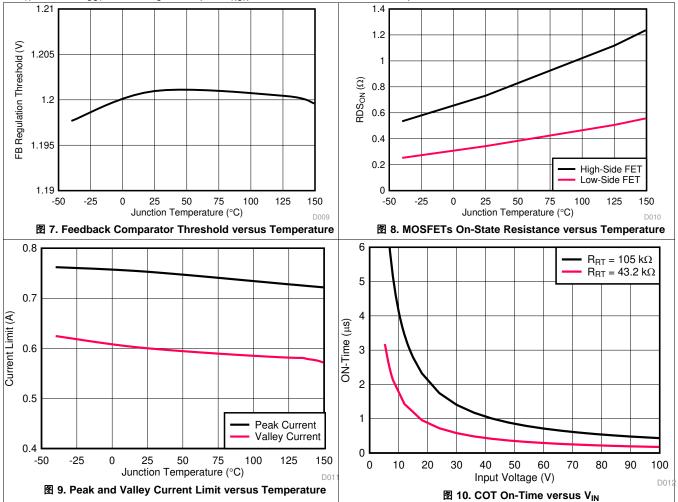
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SOFT STAR	т					
t <sub>SS</sub>	Internal soft-start time		1.75	3	4.75	ms
CURRENT L	IMIT				·	
I <sub>PEAK1</sub>	Peak current limit threshold (HS)		0.63	0.75	0.87	А
I <sub>PEAK2</sub>	Peak current limit threshold (LS)		0.63	0.75	0.87	А
I <sub>DELTA-ILIM</sub>	Min of ( $I_{PEAK1}$ or $I_{PEAK2}$ ) minus $I_{VALLEY}$			100		mA
IVALLEY	Valley current limit threshold		0.5	0.6	0.72	А
THERMAL S	HUTDOWN				·	
T <sub>SD</sub>	Thermal shutdown threshold	T <sub>J</sub> rising		175		°C
T <sub>SD-HYS</sub>	Thermal shutdown hysteresis			10		°C

## 6.6 Typical Characteristics

At T<sub>A</sub> = 25°C, V<sub>OUT</sub> = 12 V, L<sub>O</sub> = 120  $\mu$ H, R<sub>RON</sub> = 105 k $\Omega$ , unless otherwise specified.



## Typical Characteristics (接下页)



At  $T_A = 25^{\circ}$ C,  $V_{OUT} = 12$  V,  $L_O = 120 \mu$ H,  $R_{RON} = 105 k\Omega$ , unless otherwise specified.

## 7 Detailed Description

#### 7.1 Overview

The LM5163 is an easy-to-use, ultra-low  $I_Q$  constant on-time (COT) synchronous step-down buck regulator. With integrated high-side and low-side power MOSFETs, the LM5163 is a low-cost, highly efficient buck converter that operates from a wide input voltage of 6 V to 100 V, delivering up to 0.5-A DC load current. The LM5163 is available in an 8-pin SO Power PAD package with 1.27-mm pin pitch for adequate spacing in high-voltage applications. This constant on-time (COT) converter is ideal for low-noise, high-current, and fast load transient requirements, operating with a predictive on-time switching pulse. Over the input voltage range, input voltage feedforward is employed to achieve a quasi-fixed switching frequency. A controllable on-time as low as 50 ns permits high step-down ratios and a minimum forced off-time of 50 ns provides extremely high duty cycles, allowing V<sub>IN</sub> to drop close to V<sub>OUT</sub> before frequency foldback occurs. At light loads, the device transitions into an ultra-low  $I_Q$  mode to maintain high efficiency and prevent draining battery cells connected to the input when the system is in standby. The LM5163 implements a smart peak and valley current limit detection circuit to ensure robust protection during output short circuit conditions. Control loop compensation is not required for this regulator, reducing design time and external component count.

The LM5163 incorporates additional features for comprehensive system requirements, including an open-drain power good circuit for the following:

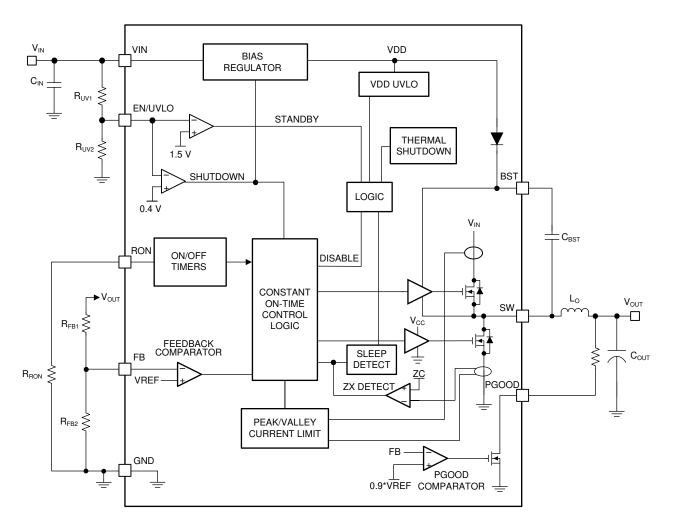
- Power-rail sequencing and fault reporting
- Internally-fixed soft start
- Monotonic start-up into prebiased loads
- Precision enable for programmable line undervoltage lockout (UVLO)
- Smart cycle-by-cycle current limit for optimal inductor sizing
- Thermal shutdown with automatic recovery

These features enable a flexible and easy-to-use platform for a wide range of applications. The LM5163 supports a wide range of end-equipment systems requiring a regulated output from a high input supply where the transient voltage deviates from the DC level. The following are examples of such end equipment systems:

- 48-V automotive systems
- High cell-count battery-pack systems
- 24-V industrial systems
- 48-V telecom and PoE voltage ranges

The pin arrangement is designed for a simple layout requiring only a few external components.

## 7.2 Functional Block Diagram



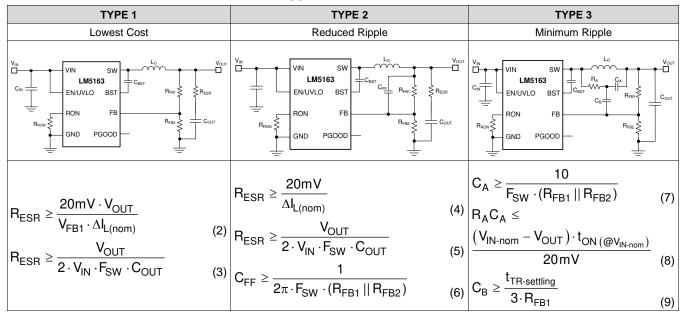
## 7.3 Feature Description

## 7.3.1 Control Architecture

The LM5163 step-down switching converter employs a constant on-time (COT) control scheme. The COT control scheme sets a fixed on-time  $t_{ON}$  of the high-side FET using a timing resistor ( $R_{ON}$ ). The  $t_{ON}$  is adjusted as Vin changes and is inversely proportional to the input voltage to maintain a fixed frequency when in continuous conduction mode (CCM). After expiration of  $t_{ON}$ , the high-side FET remains off until the feedback pin is equal or below the reference voltage of 1.2 V. To maintain stability, the feedback comparator requires a minimal ripple voltage that is in phase with the inductor current during the off-time. Furthermore, this change in feedback voltage during the off-time must be large enough to dominate any noise present at the feedback node. The minimum recommended ripple voltage is 20 mV. See  $\frac{1}{8}$  1 for different types of ripple injection schemes that ensure stability over the full input voltage range.

During a rapid start-up or a positive load step, the regulator operates with minimum off-times until regulation is achieved. This feature enables extremely fast load transient response with minimum output voltage undershoot. When regulating the output in steady-state operation, the off-time automatically adjusts itself to produce the SW-pin duty cycle required for output voltage regulation to maintain a fixed switching frequency. In CCM, the switching frequency  $F_{SW}$  is programmed by the  $R_{RON}$  resistor. Use 公式 1 to calculate the switching frequency.

$$F_{SW}(kHz) = \frac{V_{OUT}(V) \cdot 2500}{R_{RON}(k\Omega)}$$



#### 表 1. Ripple Generation Methods

表 1 presents three different methods for generating appropriate voltage ripple at the feedback node. Type-1 ripple generation method uses a single resistor,  $R_{ESR}$ , in series with the output capacitor. The generated voltage ripple has two components: capacitive ripple caused by the inductor ripple current charging and discharging the output capacitor and resistive ripple caused by the inductor ripple current flowing into the output capacitor and through series resistance  $R_{ESR}$ . The capacitive ripple component is out of phase with the inductor current and does not decrease monotonically during the off-time. The resistive ripple must exceed the capacitive ripple at V<sub>OUT</sub> for stable operation. If this condition is not satisfied, unstable switching behavior is observed in COT converters, with multiple on-time bursts in close succession followed by a long off time.  $\Delta \pm 2$  and  $\Delta \pm 3$  define the value of the series resistance  $R_{ESR}$  to ensure sufficient in-phase ripple at the feedback node.

Type-2 ripple generation uses a  $C_{FF}$  capacitor in addition to the series resistor. As the output voltage ripple is directly AC-coupled by  $C_{FF}$  to the feedback node, the  $R_{ESR}$  and ultimately the output voltage ripple are reduced by a factor of  $V_{OUT} / V_{FB1}$ .

Type-3 ripple generation uses an RC network consisting of  $R_A$  and  $C_A$ , and the switch node voltage to generate a triangular ramp that is in-phase with the inductor current. This triangular wave is the AC-coupled into the feedback node with capacitor  $C_B$ . Because this circuit does not use output voltage ripple, it is suited for applications where low output voltage ripple is critical. The *AN-1481 Controlling Output Ripple and Achieving ESR Independence in Constant On-time (COT) Regulator Designs Application Note* provides additional details on this topic.

Diode emulation mode (DEM) prevents negative inductor current, and pulse skipping maintains the highest efficiency at light load currents by decreasing the effective switching frequency. DEM operation occurs when the synchronous power MOSFET switches off as inductor valley current reaches zero. Here, the load current is less than half of the peak-to-peak inductor current ripple in CCM. Turning off the low-side MOSFET at zero current reduces switching loss, and preventing negative current conduction reduces conduction loss. Power conversion efficiency is higher in a DEM converter than an equivalent forced-PWM CCM converter. With DEM operation, the duration that both power MOSFETs remain off progressively increases as load current decreases. When this idle duration exceeds 15  $\mu$ s, the converter transitions into an ultra-low  $I_Q$  mode, consuming only 10- $\mu$ A quiescent current from the input.

#### 7.3.2 Internal VCC Regulator and Bootstrap Capacitor

The LM5163 contains an internal linear regulator that is powered from VIN with a nominal output of 5 V, eliminating the need for an external capacitor to stabilize the linear regulator. The internal VCC regulator supplies current to internal circuit blocks including the synchronous FET driver and logic circuits. The input pin (VIN) can be connected directly to line voltages up to 100 V. As the power MOSFET has a low total gate charge, use a low bootstrap capacitor value to reduce the stress on the internal regulator. It is required to select a high-quality 2.2-nF 50-V X7R ceramic bootstrap capacitor as specified in the *Absolute Maximum Ratings* section. Selecting a higher value capacitance stresses the internal VCC regulator and damages the device. A lower capacitance than required is not sufficient to drive the internal gate of the power MOSFET. An internal diode connects from the VCC regulator to the BST pin to replenish the charge in the high-side gate drive bootstrap capacitor when the SW voltage is low.

#### 7.3.3 Regulation Comparator

The feedback voltage at FB is compared to an internal 1.2-V reference. The LM5163 voltage regulation loop regulates the output voltage by maintaining the FB voltage equal to the internal reference voltage,  $V_{REF}$ . A resistor divider programs the ratio from output voltage  $V_{OUT}$  to FB.

For a target V<sub>OUT</sub> setpoint, use  $\Delta \pm 10$  to calculate R<sub>FB2</sub> based on the selected R<sub>FB1</sub>.

$$R_{FB2} = \frac{1.2 V}{V_{OUT} - 1.2 V} \cdot R_{FB1}$$
(10)

TI recommends selecting  $R_{FB1}$  in the range of 100 k $\Omega$  to 1 M $\Omega$  for most applications. A larger  $R_{FB1}$  consumes less DC current, which is mandatory if light-load efficiency is critical.  $R_{FB1}$  larger than 1 M $\Omega$  is not recommended as the feedback path becomes more susceptible to noise. It is important to route the feedback trace away from the noisy area of the PCB and keep the feedback resistors close to the FB pin.

#### 7.3.4 Internal Soft Start

The LM5163 employs an internal soft-start control ramp that allows the output voltage to gradually reach a steady-state operating point, thereby reducing start-up stresses and current surges. The soft-start feature produces a controlled, monotonic output voltage start-up. The soft-start time is internally set to 3 ms.

#### 7.3.5 On-Time Generator

The on-time of the LM5163 high-side FET is determined by the R<sub>RON</sub> resistor and is inversely proportional to the input voltage, V<sub>IN</sub>. The inverse relationship with V<sub>IN</sub> results in a nearly constant frequency as V<sub>IN</sub> is varied. Use  $\pm$  11 to calculate the on-time.

$$t_{ON}(\mu s) = \frac{R_{RON}(k\Omega)}{V_{IN}(V) \cdot 2.5}$$
(11)

Use 公式 12 to determine the  $R_{RON}$  resistor to set a specific switching frequency in CCM.

$$R_{RON}(k\Omega) = \frac{V_{OUT}(V) \cdot 2500}{F_{SW}(kHz)}$$
(12)

Select  $R_{RON}$  for a minimum on-time (at maximum  $V_{IN}$ ) greater than 50 ns for proper operation. In addition to this minimum on-time, the maximum frequency for this device is limited to 1 MHz.

#### 7.3.6 Current Limit

The LM5163 manages overcurrent conditions with cycle-by-cycle current limiting of the peak inductor current. The current sensed in the high-side MOSFET is compared every switching cycle to the current limit threshold (0.75 A). To protect the converter from potential current runaway conditions, the LM5163 includes a foldback valley current limit feature, set at 0.6 A, that is enabled if a peak current limit is detected. As shown in 🕅 11, if the peak current in the high-side MOSFET exceeds 0.75 A (typical), the present cycle is immediately terminated

regardless of the programmed on-time ( $t_{ON}$ ), the high-side MOSFET is turned off and the foldback valley current limit is activated. The low-side MOSFET remains on until the inductor current drops below this foldback valley current limit, after which the next on-pulse is initiated. This method folds back the switching frequency to prevent overheating and limits the average output current to less than 0.75 A to ensure proper short-circuit and heavy-load protection of the LM5163.

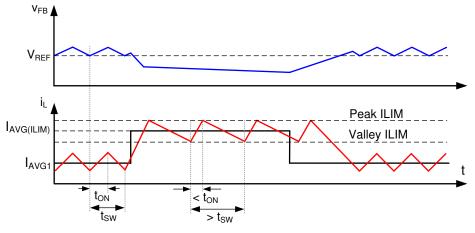


图 11. Current Limit Timing Diagram

Current is sensed after a leading-edge blanking time following the high-side MOSFET turnon transition. The propagation delay of the current limit comparator is 100 ns. During high step-down conditions when the on-time is less than 100 ns, a back-up peak current limit comparator in the low-side FET also set at 0.75 A enables the foldback valley current limit set at 0.6 A. This innovative current limit scheme enables ultra-low duty-cycle operation, permitting large step-down voltage conversions while ensuring robust protection of the converter.

#### 7.3.7 N-Channel Buck Switch and Driver

The LM5163 integrates an N-channel buck switch and associated floating high-side gate driver. The gate-driver circuit works in conjunction with an external bootstrap capacitor and an internal high-voltage bootstrap diode. A high-quality 2.2-nF, 50-V X7R ceramic capacitor connected between the BST and SW pins provides the voltage to the high-side driver during the buck switch on-time. See the *Internal VCC Regulator and Bootstrap Capacitor* section for limitations. During the off-time, the SW pin is pulled down to approximately 0 V, and the bootstrap capacitor charges from the internal VCC through the internal bootstrap diode. The minimum off-timer, set to 50 ns (typical), ensures a minimum time each cycle to recharge the bootstrap capacitor. When the on-time is less than 300 ns, the minimum off-timer is forced to 250 ns to ensure that the BST capacitor is charged in a single cycle. This is vital during wake up from sleep mode when the BST capacitor is most likely discharged.

#### 7.3.8 Synchronous Rectifier

The LM5163 provides an internal low-side synchronous rectifier N-channel MOSFET. This MOSFET provides a low-resistance path for the inductor current to flow when the high-side MOSFET is turned off.

The synchronous rectifier operates in a diode emulation mode. Diode emulation enables the regulator to operate in a pulse-skipping mode during light load conditions. This mode leads to a reduction in the average switching frequency at light loads. Switching losses and FET gate driver losses, both of which are proportional to switching frequency, are significantly reduced at very light loads and efficiency is improved. This pulse-skipping mode also reduces the circulating inductor current and losses associated with conventional CCM at light loads.

#### 7.3.9 Enable/Undervoltage Lockout (EN/UVLO)

The LM5163 contains a dual-level EN/UVLO circuit. When the EN/UVLO voltage is below 1.1 V (typical), the converter is in a low-current shutdown mode and the input quiescent current ( $I_Q$ ) is dropped down to 3 µA. When the voltage is greater than 1.1 V but less than 1.5 V (typical), the converter is in standby mode. In standby mode the internal bias regulator is active while the control circuit is disabled. When the voltage exceeds the rising threshold of 1.5 V (typical), normal operation begins. Install a resistor divider from VIN to GND to set the minimum operating voltage of the regulator. Use  $\Delta \pm 13$  and  $\Delta \pm 14$  to calculate the input UVLO turnon and turnoff voltages, respectively.

$$V_{\rm IN(on)} = 1.5 \, \mathrm{V} \cdot \left( 1 + \frac{\mathrm{R}_{\rm UV1}}{\mathrm{R}_{\rm UV2}} \right) \tag{13}$$

$$V_{\rm IN(off)} = 1.4 \, \mathrm{V} \cdot \left( 1 + \frac{1.001}{\mathrm{R}_{\rm UV2}} \right) \tag{14}$$

TI recommends selecting  $R_{UV1}$  in the range of 1 M $\Omega$  for most applications. A larger  $R_{UV1}$  consumes less DC current, which is mandatory if light-load efficiency is critical. If input UVLO is not required, the power-supply designer can either drive EN/UVLO as an enable input driven by a logic signal or connect it directly to VIN. If EN/UVLO is directly connected to VIN, the regulator begins switching as soon as the internal bias rails are active.

#### 7.3.10 Power Good (PGOOD)

The LM5163 provides a PGOOD flag pin to indicate when the output voltage is within the regulation level. Use the PGOOD signal for start-up sequencing of downstream converters or for fault protection and output monitoring. PGOOD is an open-drain output that requires a pullup resistor to a DC supply not greater than 14 V. The typical range of pullup resistance is 10 k $\Omega$  to 100 k $\Omega$ . If necessary, use a resistor divider to decrease the voltage from a higher voltage pullup rail. When the FB voltage exceeds 95% of the internal reference V<sub>REF</sub>, the internal PGOOD switch turns off and PGOOD can be pulled high by the external pullup. If the FB voltage falls below 90% of V<sub>REF</sub>, an internal 25- $\Omega$  PGOOD switch turns on and PGOOD is pulled low to indicate that the output voltage is out of regulation. The rising edge of PGOOD has a built-in deglitch delay of 5 µs.

#### 7.3.11 Thermal Protection

The LM5163 includes an internal junction temperature monitor to protect the device in the event of a higher than normal junction temperature. If the junction temperature exceeds 175°C (typical), thermal shutdown occurs to prevent further power dissipation and temperature rise. The LM5163 initiates a restart sequence when the junction temperature falls to 165°C, based on a typical thermal shutdown hysteresis of 10°C. This is a non-latching protection, so the device cycles into and out of thermal shutdown if the fault persists.

### 7.4 Device Functional Modes

#### 7.4.1 Shutdown Mode

EN/UVLO provides ON and OFF control for the LM5163. When  $V_{EN/UVLO}$  is below approximately 1.1 V, the device is in shutdown mode. Both the internal linear regulator and the switching regulator are off. The quiescent current in shutdown mode drops to 3  $\mu$ A at  $V_{IN} = 24$  V. The LM5163 also employs internal bias rail undervoltage protection. If the internal bias supply voltage is below the UV threshold, the regulator remains off.

#### 7.4.2 Active Mode

The LM5163 is in active mode when  $V_{EN/UVLO}$  is above the precision enable threshold and the internal bias rail is above its UV threshold. In COT active mode, the LM5163 is in one of three modes depending on the load current:

- 1. CCM with fixed switching frequency when load current is above half of the peak-to-peak inductor current ripple
- 2. Pulse skipping and diode emulation mode (DEM) when the load current is less than half of the peak-to-peak inductor current ripple in CCM operation
- 3. Current limit CCM with peak and valley current limit protection when an overcurrent condition is applied at the output

#### 7.4.3 Sleep Mode

The *Control Architecture* section gives a brief introduction to the LM5163 diode emulation (DEM) feature. The converter enters DEM during light-load conditions when the inductor current decays to zero and the synchronous MOSFET is turned off to prevent negative current in the system. In the DEM state, the load current is lower than half of the peak-to-peak inductor current ripple and the switching frequency decreases when the load is further decreased as the device operates in a pulse skipping mode. A switching pulse is set when  $V_{FB}$  drops below 1.2 V.

As the frequency of operation decreases and  $V_{FB}$  remains above 1.2 V ( $V_{REF}$ ) with the output capacitor sourcing the load current for greater than 15 µs, the converter enters an ultra-low  $I_Q$  sleep mode to prevent draining the input power supply. The input quiescent current ( $I_Q$ ) required by the LM5163 decreases to 10 µA in sleep mode, improving the light-load efficiency of the regulator. In this mode, all internal controller circuits are turned off to ensure very low current consumption by the device. Such low  $I_Q$  renders the LM5163 as the best option to extend operating lifetime for off-battery applications. The FB comparator and internal bias rail are active to detect when the FB voltage drops below the internal reference  $V_{REF}$  and the converter transitions out of sleep mode into active mode. There is a 9-µs wake-up delay from sleep to active states.

## 8 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

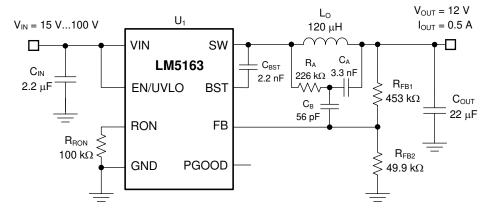
#### 8.1 Application Information

The LM5163 requires only a few external components to step down from a wide range of supply voltages to a fixed output voltage. Several features are integrated to meet system design requirements, including the following:

- Precision enable
- Input voltage UVLO
- Internal soft start
- Programmable switching frequency
- A PGOOD indicator

To expedite and streamline the process of designing of a LM5163-based converter, a comprehensive LM5163 quickstart calculator is available for download to assist the designer with component selection for a given application. This tool is complemented by the availability of an evaluation module (EVM), numerous PSPICE models, as well as TI's WEBENCH® Power Designer. In order to modify the LM5164-Q1EVM-041 for the LM5163-Q1, change the inductor  $L_0$  to 120 µH, the resistor  $R_A$  to 226 k $\Omega$ , and the capacitance  $C_{OUT}$  to 22 µF. See  $\mathbb{R}$  12 for the LM5163-Q1 applications circuit.

#### 8.2 Typical Application



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图 12. Typical Application  $V_{IN(nom)}$  = 48 V,  $V_{OUT}$  = 12 V,  $I_{OUT(max)}$  = 0.5 A,  $F_{SW(nom)}$  = 300 kHz

注

This and subsequent design examples are provided herein to showcase the LM5163 converter in several different applications. Depending on the source impedance of the input supply bus, an electrolytic capacitor may be required at the input to ensure stability, particularly at low input voltage and high output current operating conditions. See the *Power Supply Recommendations* section for more details.

## Typical Application (接下页)

#### 8.2.1 Design Requirements

The target full-load efficiency is 92% based on a nominal input voltage of 48 V and an output voltage of 12 V. The required input voltage range is 15 V to 100 V. The LM5163 delivers a fixed 12-V output voltage. The switching frequency is set by resistor  $R_{RON}$  at 300 kHz. The output voltage soft-start time is 3 ms.  $\frac{12}{2}$  lists the required components. Refer to the *LM5164-Q1EVM-041 User's Guide* for more detail.

COUNT	REF DES	VALUE	DESCRIPTION	PART NUMBER	MANUFACTURER
2	C <sub>IN</sub>	2.2 µF	Capacitor, Ceramic, 2.2 µF, 100 V, X7R, 10%	CGA6N3X7R2A225K230AB	TDK
1	C <sub>OUT</sub>	22 µF	Capacitor, Ceramic, 22 µF, 25 V, X7R, 10%	TMK325B7226KMHT	Taiyo Yuden
1	C <sub>A</sub>	3300 pF	Capacitor, Ceramic, 3300 pF, 16 V, X7R, 10%	CGA3E2X7R2A332K080AA	TDK
1	C <sub>B</sub>	56 pF	Capacitor, Ceramic, 56 pF, 50 V, X7R, 10%	C0603C560J5GACTU	Kemet
1	C <sub>BST</sub>	2.2 nF	Capacitor, Ceramic, 2200 pF, 50 V, X7R, 10%	GCM155R71H222KA37D	MuRata
1	Lo	120 µH	Inductor, 120 μH, 210 mΩ, 1.65 A	MSS1260-124KL	Coilcraft
1	R <sub>RON</sub>	100 kΩ	Resistor, Chip, 100 k, 1%, 0.1 W, 0603	RG1608P-1053-B-T5	Susumu Co Ltd
1	R <sub>FB1</sub>	453 kΩ	Resistor, Chip, 453 k, 1%, 0.1 W, 0603	RT0603BRD07448KL	Yageo
1	R <sub>FB2</sub>	49.9 kΩ	Resistor, Chip, 49.9 k, 1%, 0.1 W, 0603	RG1608P-4992-B-T5	Susumu Co Ltd
1	R <sub>A</sub>	226 kΩ	Resistor, Chip, 226 k, 1%, 0.1W, 0603	RT0603BRD07226KL	Yageo
1	U <sub>1</sub>		Wide V <sub>IN</sub> synchronous buck converter	LM5163DDAR	ТІ

表 2. List of Components

#### 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5163 device with the WEBENCH® Power Designer.

- 1. Start by entering the input voltage (V<sub>IN</sub>), output voltage (V<sub>OUT</sub>), and output current (I<sub>OUT</sub>) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
- 3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

#### 8.2.2.2 Switching Frequency (R<sub>RON</sub>)

The switching frequency of the LM5163 is set by the on-time programming resistor placed at RON. As shown by  $\Delta \vec{x}$  15, a standard 100 k $\Omega$ , 1% resistor sets the switching frequency at 300 kHz.

$$\mathsf{R}_{\mathsf{RON}}(\mathsf{k}\Omega) = \frac{\mathsf{V}_{\mathsf{OUT}}(\mathsf{V}) \cdot 2500}{\mathsf{F}_{\mathsf{SW}}(\mathsf{k}\mathsf{Hz})}$$

(15)

Note that at very low duty cycles, the 50 ns minimum controllable on-time of the high-side MOSFET,  $t_{ON(min)}$ , limits the maximum switching frequency. In CCM,  $t_{ON(min)}$  limits the voltage conversion step-down ratio for a given switching frequency. Use  $\Delta \pm 16$  to calculate the minimum controllable duty cycle.

(16)

Ultimately, the choice of switching frequency for a given output voltage affects the available input voltage range, solution size, and efficiency. Use 公式 17 to calculate the maximum supply voltage for a given  $t_{ON(min)}$  before switching frequency reduction occurs.

$$V_{IN(max)} = rac{V_{OUT}}{t_{ON(min)} \cdot F_{SW}}$$

## 8.2.2.3 Buck Inductor ( $L_{O}$ )

Use 公式 18 and 公式 19 to calculate the inductor ripple current (assuming CCM operation) and peak inductor current, respectively.

$$\Delta I_{L} = \frac{V_{OUT}}{F_{SW} \cdot L_{O}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

$$I_{L(peak)} = I_{OUT(max)} + \frac{\Delta I_{L}}{2}$$
(19)

For most applications, choose an inductance such that the inductor ripple current,  $\Delta I_L$ , is between 30% and 50% of the rated load current at nominal input voltage. Use  $\Delta \vec{x}$  20 to calculate the inductance.

$$L_{O} = \frac{V_{OUT}}{F_{SW} \cdot \Delta I_{L}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN(nom)}}\right)$$
(20)

Choosing a  $120-\mu$ H inductor in this design results in 250-mA peak-to-peak ripple current at a nominal input voltage of 48 V, equivalent to 50% of the 500-mA rated load current.

Check the inductor data sheet to make sure the saturation current of the inductor is well above the current limit setting of the LM5163. Ferrite-core inductors have relatively lower core losses and are preferred at high switching frequencies, but exhibit a hard saturation characteristic – the inductance collapses abruptly when the saturation current is exceeded. This results in an abrupt increase in inductor ripple current, higher output voltage ripple, and reduced efficiency, in turn compromising reliability. Note that inductor saturation current levels generally decrease as the core temperature increases.

#### 8.2.2.4 Output Capacitor (C<sub>OUT</sub>)

Select a ceramic output capacitor to limit the capacitive voltage ripple at the converter output. This is the sinusoidal ripple voltage that is generated from the triangular inductor current ripple flowing into and out of the capacitor. Select an output capacitance using  $\Delta$  $<math> \pm$  21 to limit the voltage ripple component to 0.5% of the output voltage.

$$C_{OUT} \geq \frac{\Delta I_{L}}{8 \cdot F_{SW} \cdot V_{OUT(ripple)}}$$

Substituting  $\Delta I_{L(nom)}$  of 250-mA gives C<sub>OUT</sub> greater than 3.1  $\mu$ F. With voltage coefficients of ceramic capacitors taken in consideration, a 22- $\mu$ F, 25-V rated capacitor with X7R dielectric is selected.

#### 8.2.2.5 Input Capacitor (C<sub>IN</sub>)

An input capacitor is necessary to limit the input ripple voltage while providing AC current to the buck power stage at every switching cycle. To minimize the parasitic inductance in the switching loop, position the input capacitors as close as possible to the VIN and GND pins of the LM5163. The input capacitors conduct a square-wave current of peak-to-peak amplitude equal to the output current. It follows that the resultant capacitive component of AC ripple voltage is a triangular waveform.

Along with the ESR-related ripple component, use 公式 22 to calculate the peak-to-peak ripple voltage amplitude.

$$V_{IN(ripple)} = \frac{I_{OUT} \cdot D \cdot (1 - D)}{F_{SW} \cdot C_{IN}} + I_{OUT} \cdot R_{ESR}$$

(22)

(21)

Use  $\Delta \pm 23$  to calculate the input capacitance required for a load current, based on an input voltage ripple specification ( $\Delta VIN$ ).

$$C_{IN} \ge \frac{I_{OUT} \cdot D \cdot (1 - D)}{F_{SW} \cdot (V_{IN(ripple)} - I_{OUT} \cdot R_{ESR})}$$
(23)

The recommended high-frequency input capacitance is 2.2  $\mu$ F or higher. Ensure the input capacitor is a highquality X7S or X7R ceramic capacitor with sufficient voltage rating for C<sub>IN</sub>. Based on the voltage coefficient of ceramic capacitors, choose a voltage rating of twice the maximum input voltage. Additionally, some bulk capacitance is required if the LM5163 is not located within approximately 5 cm from the input voltage source. This capacitor provides parallel damping to the resonance associated with parasitic inductance of the supply lines and high-Q ceramics. See the *Power Supply Recommendations* section for more detail.

#### 8.2.2.6 Type 3 Ripple Network

A Type 3 ripple generation network uses an RC filter consisting of  $R_A$  and  $C_A$  across SW and  $V_{OUT}$  to generate a triangular ramp that is in phase with the inductor current. This triangular ramp is then AC-coupled into the feedback node using capacitor  $C_B$  as shown in  $\mathbb{R}$  12. Type 3 ripple injection is suited for applications where low output voltage ripple is crucial.

Use 公式 24 and 公式 25 to calculate  $R_A$  and  $C_A$  to provide the required ripple amplitude at the FB pin.

$$C_{A} \geq \frac{10}{F_{SW} \cdot \left(R_{FB1} \| R_{FB2}\right)}$$
(24)

For the feedback resistor values given in  $\[Begin{subarray}{c} 12,\ \Delta \Cite{L}\ 24\ dictates\ a\ minimum\ C_A\ of\ 742\ pF.$  In this design, a 3300 pF capacitance is chosen. This is done to keep R<sub>A</sub> within practical limits between 100 k $\Omega$  and 1 M $\Omega$  when using  $\Delta \Cite{L}\ 25$ .

$$R_{A}C_{A} \geq \frac{\left(V_{IN(nom)} - V_{OUT}\right) \cdot t_{ON(nom)}}{20mV}$$
(25)

Based on C<sub>A</sub> set at 3.3 nF, R<sub>A</sub> is calculated to be 226 k $\Omega$  to provide a 20-mV ripple voltage at FB. The general recommendation for a Type 3 network is to calculate R<sub>A</sub> and C<sub>A</sub> to get 20 mV of ripple at typical operating conditions, while ensuring a 12-mV minimum ripple voltage on FB at minimum V<sub>IN</sub>.

While the amplitude of the generated ripple does not affect the output voltage ripple, it impacts the output regulation as it reflects as a DC error of approximately half the amplitude of the generated ripple. For example, a converter circuit with Type 3 network that generates a 40-mV ripple voltage at the feedback node has approximately 10-mV worse load regulation scaled up through the FB divider to  $V_{OUT}$  than the same circuit that generates a 20-mV ripple at FB. Use  $\Delta \pm 26$  to calculate the coupling capacitance C<sub>B</sub>.

$$C_{B} \geq \frac{t_{TR-settling}}{3 \cdot R_{FB1}}$$

where

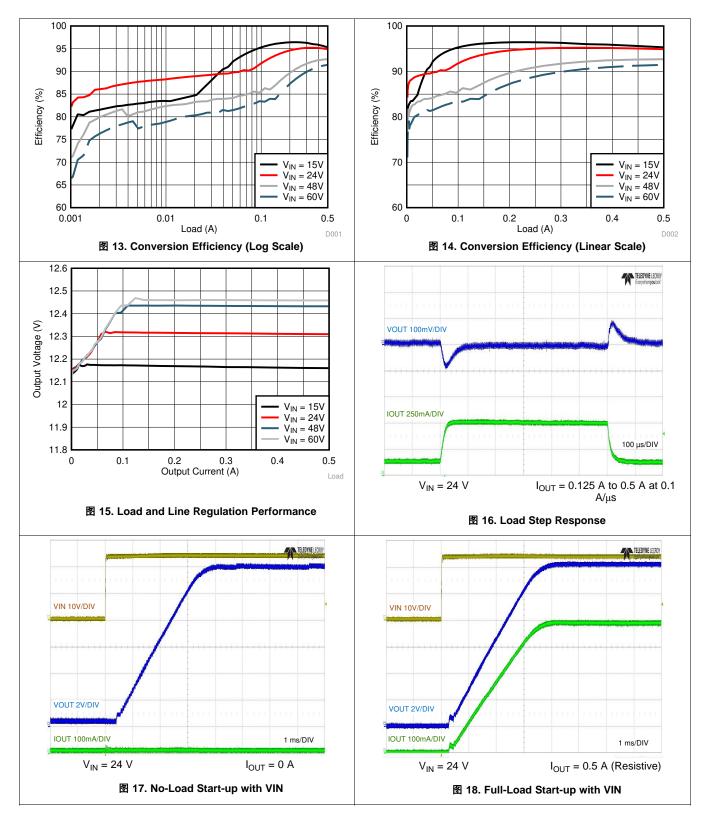
• t<sub>TR-settling</sub> is the desired load transient response settling time

 $C_B$  calculates to 56 pF based on a 75-µs settling time. This value avoids excessive coupling capacitor discharge by the feedback resistors during sleep intervals when operating at light loads. To avoid capacitance fall-off with DC bias, use a COG or NP0 dielectric capacitor for  $C_B$ .

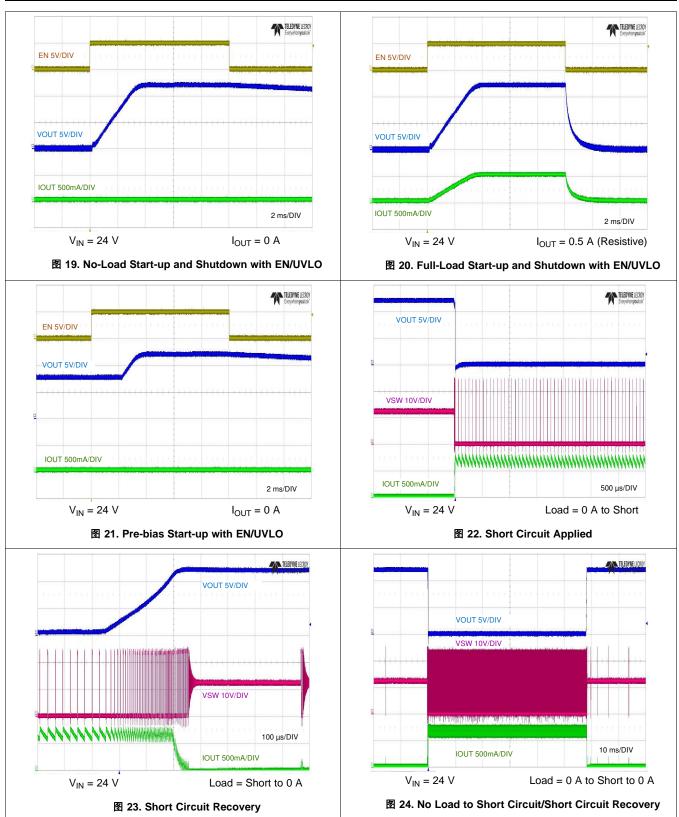
(25)

(26)

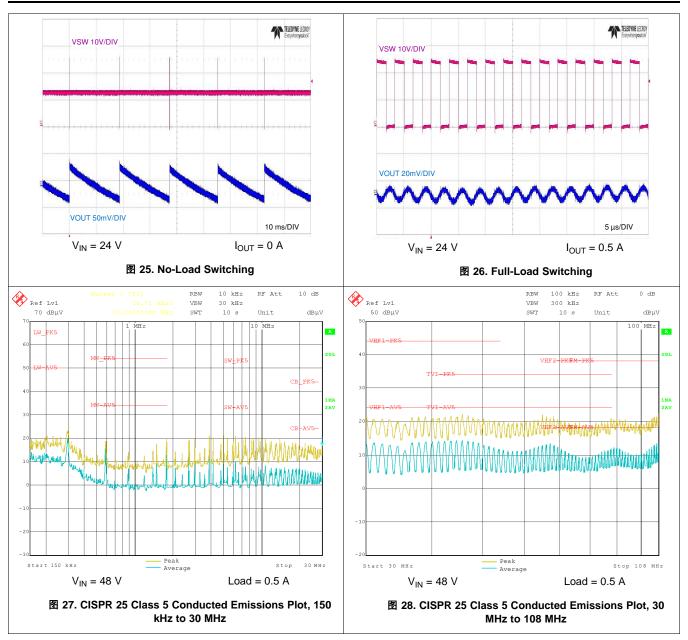
#### 8.2.3 Application Curves



LM5163 ZHCSKD6-OCTOBER 2019



LM5163 ZHCSKD6-OCTOBER 2019



## 9 Power Supply Recommendations

The LM5163 buck converter is designed to operate from a wide input voltage range between 6 V and 100 V. The characteristics of the input supply must be compatible with the *Absolute Maximum Ratings* and *Recommended Operating Conditions* tables. In addition, the input supply must be capable of delivering the required input current to the fully-loaded regulator. Use 公式 27 to estimate the average input current.

where

• η is the efficiency

(27)

If the converter is connected to an input supply through long wires or PCB traces with a large impedance, take special care to achieve stable performance. The parasitic inductance and resistance of the input cables can have an adverse affect on converter operation. The parasitic inductance in combination with the low-ESR ceramic input capacitors form an underdamped resonant circuit. This circuit can cause overvoltage transients at VIN each time the input supply is cycled ON and OFF. The parasitic resistance causes the input voltage to dip during a load transient. If the converter is operating close to the minimum input voltage, this dip can cause false UVLO fault triggering and a system reset. The best way to solve such issues is to reduce the distance from the input supply to the regulator and use an aluminum electrolytic input capacitor in parallel with the ceramics. The moderate ESR of the electrolytic capacitor helps to damp the input resonant circuit and reduce any voltage overshoots. A 10- $\mu$ F electrolytic capacitor with a typical ESR of 0.5  $\Omega$  provides enough damping for most input circuit configurations.

An EMI input filter is often used in front of the regulator that, unless carefully designed, can lead to instability as well as some of the effects mentioned above. The *Simple Success with Conducted EMI for DC-DC Converters Application Report* provides helpful suggestions when designing an input filter for any switching regulator.

## 10 Layout

#### **10.1 Layout Guidelines**

PCB layout is a critical portion of good power supply design. There are several paths that conduct high slew-rate currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise and EMI or degrade the power supply performance.

- 1. To help eliminate these problems, bypass the VIN pin to GND with a low-ESR ceramic bypass capacitor with a high-quality dielectric. Place  $C_{IN}$  as close as possible to the LM5163 VIN and GND pins. Grounding for both the input and output capacitors must consist of localized top-side planes that connect to the GND pin and GND PAD.
- 2. Minimize the loop area formed by the input capacitor connections to the VIN and GND pins.
- 3. Locate the inductor close to the SW pin. Minimize the area of the SW trace or plane to prevent excessive capacitive coupling.
- 4. Tie the GND pin directly to the power pad under the device and to a heat-sinking PCB ground plane.
- 5. Use a ground plane in one of the middle layers as a noise shielding and heat dissipation path.
- 6. Have a single-point ground connection to the plane. Route the ground connections for the feedback, softstart, and enable components to the ground plane. This prevents any switched or load currents from flowing in analog ground traces. If not properly handled, poor grounding results in degraded load regulation or erratic output voltage ripple behavior.
- 7. Make V<sub>IN</sub>, V<sub>OUT</sub> and ground bus connections as wide as possible. This reduces any voltage drops on the input or output paths of the converter and maximizes efficiency.
- 8. Minimize trace length to the FB pin. Place both feedback resistors, R<sub>FB1</sub> and R<sub>FB2</sub>, close to the FB pin. Place C<sub>FF</sub> (if needed) directly in parallel with R<sub>FB1</sub>. If output setpoint accuracy at the load is important, connect the V<sub>OUT</sub> sense at the load. Route the V<sub>OUT</sub> sense path away from noisy nodes and preferably through a layer on the other side of a grounded shielding layer.
- The RON pin is sensitive to noise. Thus, locate the R<sub>RON</sub> resistor as close as possible to the device and route with minimal lengths of trace. The parasitic capacitance from RON to GND must not exceed 20 pF.
- 10. Provide adequate heat sinking for the LM5163 to keep the junction temperature below 150°C. For operation at full rated load, the top-side ground plane is an important heat-dissipating area. Use an array of heat-sinking vias to connect the exposed pad to the PCB ground plane. If the PCB has multiple copper layers, these thermal vias must also be connected to inner layer heat-spreading ground planes.

#### 10.1.1 Compact PCB Layout for EMI Reduction

Radiated EMI generated by high di/dt components relates to pulsing currents in switching converters. The larger area covered by the path of a pulsing current, the more electromagnetic emission is generated. The key to minimizing radiated EMI is to identify the pulsing current path and minimize the area of that path.

## Layout Guidelines (接下页)

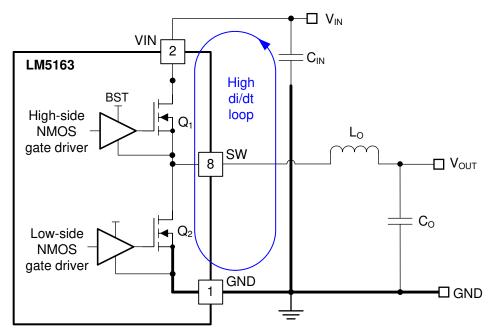


图 29. DC/DC Buck Converter With Power Stage Circuit Switching Loop

The input capacitor provides the primary path for the high di/dt components of the current of the high-side MOSFET. Placing a ceramic capacitor as close as possible to the VIN and GND pins is the key to EMI reduction. Keep the trace connecting SW to the inductor as short as possible and just wide enough to carry the load current without excessive heating. Use short, thick traces or copper pours (shapes) for current conduction path to minimize parasitic resistance. Place the output capacitor close to the V<sub>OUT</sub> side of the inductor, and connect the return terminal of the capacitor to the GND pin and exposed PAD of the LM5163.

#### 10.1.2 Feedback Resistors

Reduce noise sensitivity of the output voltage feedback path by placing the resistor divider close to the FB pin, rather than close to the load. This reduces the trace length of FB signal and noise coupling. The FB pin is the input to the feedback comparator, and as such, is a high impedance node sensitive to noise. The output node is a low impedance node, so the trace from  $V_{OUT}$  to the resistor divider can be long if a short path is not available.

Route the voltage sense trace from the load to the feedback resistor divider, keeping away from the SW node, the inductor, and  $V_{IN}$  to avoid contaminating the feedback signal with switch noise, while also minimizing the trace length. This is most important when high feedback resistances greater than 100 k $\Omega$  are used to set the output voltage. Also, route the voltage sense trace on a different layer from the inductor, SW node, and  $V_{IN}$  so there is a ground plane that separates the feedback trace from the inductor and SW node copper polygon. This provides further shielding for the voltage feedback path from switching noise sources.

## 10.2 Layout Example

图 30 shows an example layout for the PCB top layer of a 2-layer board with essential components placed on the top side.

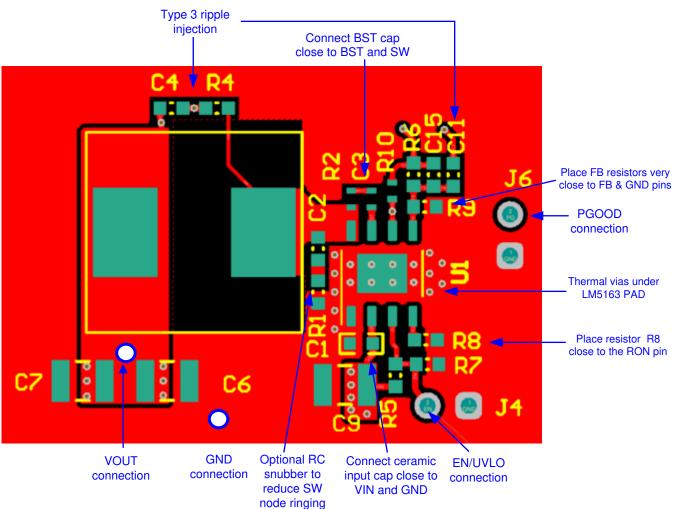


图 30. LM5163 Single-Sided PCB Layout Example

## 11 器件和文档支持

#### 11.1 器件支持

#### 11.1.1 第三方产品免责声明

TI 发布的与第三方产品或服务有关的信息,不能构成与此类产品或服务或保修的适用性有关的认可,不能构成此类产品或服务单独或与任何 TI 产品或服务一起的表示或认可。

#### 11.1.2 开发支持

- LM5163 快速入门计算器
- LM5163 仿真模型
- TI 参考设计库
- 技术文章:
  - 使用低静态电流开关进行高电压转换
  - 为工业应用中的智能传感器发送器供电
  - Industrial Strength 设计 第 1 部分
  - 楼宇自动化趋势: 预测性维护
  - 楼宇自动化趋势: 用于改善用户舒适度的互联传感器

#### 11.1.2.1 使用 WEBENCH® 工具创建定制设计

单击此处以使用带 WEBENCH® 电源设计器的 LM5163 器件来创建定制设计。

- 1. 首先输入输入电压 (V<sub>IN</sub>)、输出电压 (V<sub>OUT</sub>) 和输出电流 (I<sub>OUT</sub>) 要求。
- 2. 使用优化器拨盘优化该设计的关键参数,如效率、尺寸和成本。
- 3. 将生成的设计与德州仪器 (TI) 的其他可行的解决方案进行比较。

WEBENCH 电源设计器可提供定制原理图以及罗列实时价格和组件供货情况的物料清单。

在多数情况下,可执行以下操作:

- 运行电气仿真,观察重要波形以及电路性能
- 运行热性能仿真,了解电路板热性能
- 将定制原理图和布局方案以常用 CAD 格式导出
- 打印设计方案的 PDF 报告并与同事共享

有关 WEBENCH 工具的详细信息,请访问 www.ti.com.cn/WEBENCH。

## 11.2 相关文档

请参阅如下相关文档:

- 德州仪器 (TI), 《LM5164-Q1EVM-041 EVM 用户指南》
- 德州仪器 (TI), 《为您的 COT 降压转换器选择理想的纹波生成网络应用报告》
- 德州仪器 (TI), 《评估适用于具有成本效益的严苛应用的宽 V<sub>IN</sub>、低 EMI 同步降压 电路 白皮书》
- 德州仪器 (TI), 《电源的传导 EMI 规格概述白皮书》
- 德州仪器 (TI), 《电源的辐射 EMI 规格概述白皮书》
- 德州仪器 (TI), 《适用于智能恒温器且具有宽 V<sub>IN</sub> 转换器和电池电量计的 24V 交流功率级设计指南》
- 德州仪器 (TI), 《精确计量和 50µA 待机电流、13 节、48V 锂离子电池组参考设计指南》
- 德州仪器 (TI), 《AN-2162: 轻松抑制直流/直流转换器中的传导 EMI 应用报告》
- 德州仪器 (TI), 《利用宽 V<sub>IN</sub> 直流/直流转换器为无人机供电应用报告》
- 德州仪器 (TI), 《使用新的热指标应用报告》
- 德州仪器 (TI), 《半导体和 IC 封装热指标应用报告》

#### 11.3 接收文档更新通知

要接收文档更新通知,请导航至 ti.com. 上的器件产品文件夹。单击右上角的通知我进行注册,即可每周接收产品 信息更改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

## 11.4 支持资源

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 11.5 商标

PowerPAD, E2E are trademarks of Texas Instruments. WEBENCH is a registered trademark of Texas Instruments. All other trademarks are the property of their respective owners.

#### 11.6 静电放电警告

▶ 这些装置包含有限的内置 ESD 保护。存储或装卸时,应将导线一起截短或将装置放置于导电泡棉中,以防止 MOS 门极遭受静电损 伤。

#### 11.7 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

## 12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更, 恕不另行通知, 且 不会对此文档进行修订。如需获取此数据表的浏览器版本, 请查阅左侧的导航栏。

10-Dec-2020

## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LM5163DDAR	ACTIVE	SO PowerPAD	DDA	8	2500	RoHS & Green	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 150	LM5163	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <= 1000ppm threshold. Antimony trioxide based flame retardants must also meet the <= 1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(<sup>6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

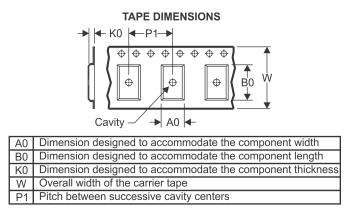
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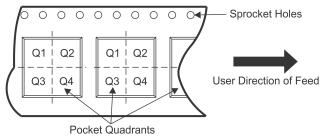
8-May-2021

#### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

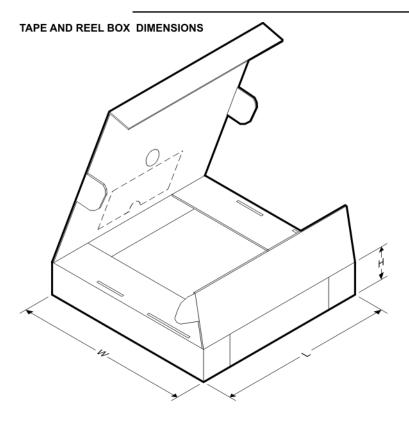


*All dimensions are nominal
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Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM5163DDAR	SO Power PAD	DDA	8	2500	330.0	12.8	6.4	5.2	2.1	8.0	12.0	Q1

## PACKAGE MATERIALS INFORMATION

8-May-2021

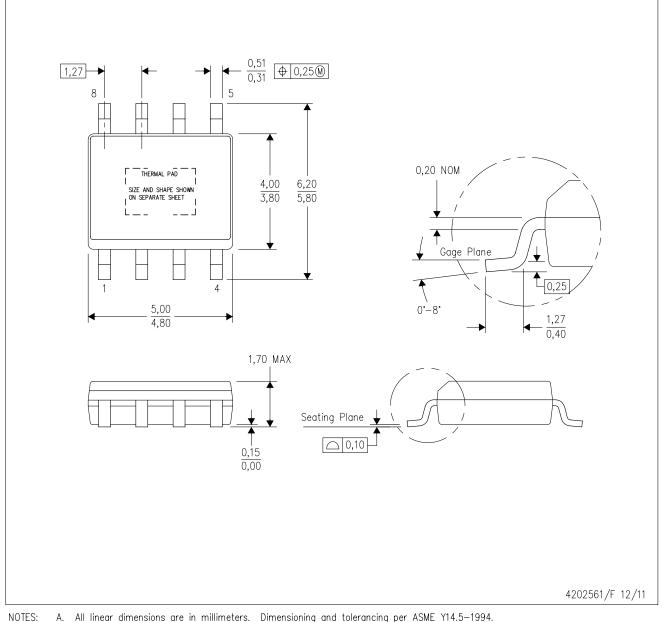


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM5163DDAR	SO PowerPAD	DDA	8	2500	366.0	364.0	50.0

DDA (R-PDSO-G8)

PowerPAD <sup>™</sup> PLASTIC SMALL-OUTLINE



- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
- F. This package complies to JEDEC MS-012 variation BA

#### PowerPAD is a trademark of Texas Instruments.

## DDA (R-PDSO-G8)

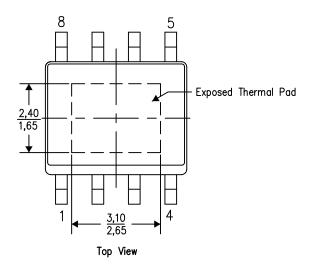
# PowerPAD<sup>™</sup> PLASTIC SMALL OUTLINE

## THERMAL INFORMATION

This PowerPAD<sup> $\mathbf{M}$ </sup> package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Exposed Thermal Pad Dimensions

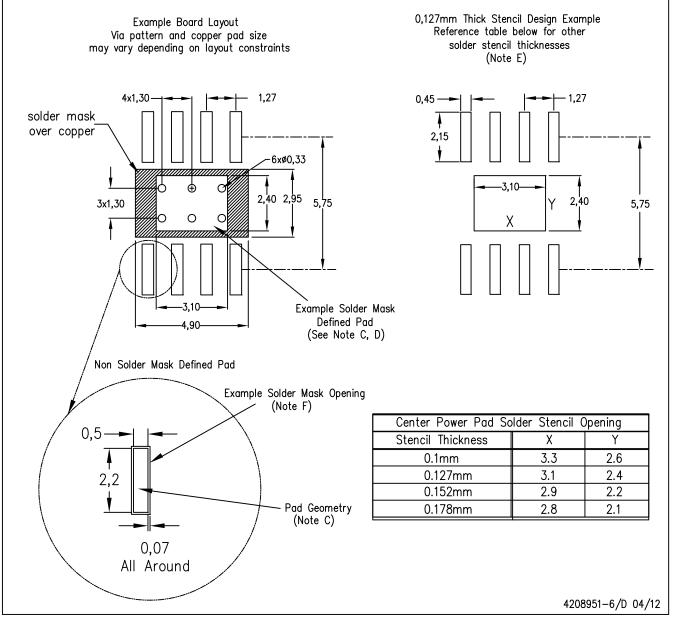
4206322-6/L 05/12

NOTE: A. All linear dimensions are in millimeters

PowerPAD is a trademark of Texas Instruments

## DDA (R-PDSO-G8)

## PowerPAD<sup>™</sup> PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
- F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads. PowerPAD is a trademark of Texas Instruments.

#### 重要声明和免责声明

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